RC4156/RC4157

High Performance Quad Operational Amplifiers

Features

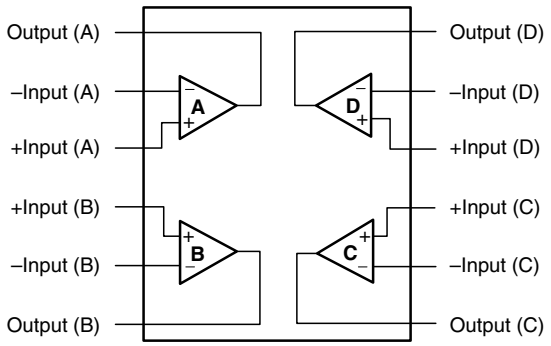
- Unity gain bandwidth for RC4156 – 3.5 MHz
- Unity gain bandwidth for RC4157 – 19 MHz
- High slew rate for RC4156 – 1.6 V/µS
- High slew rate for RC4157 – 8.0V/µS
- Low noise voltage – 1.4 µVRMS
- Indefinite short circuit protection
- No crossover distortion

Description

The RC4156 and RC4157 are monolithic integrated circuits, consisting of four independent high performance operational amplifiers constructed with an advanced epitaxial process.

These amplifiers feature improved AC performance which far exceeds that of the 741 type amplifiers. Also featured are excellent input characteristics and low noise, making this device the optimum choice for audio, active filter and instrumentation applications. The RC4157 is a decompensated version of the RC4156 and is AC stable in gain configurations of -5 or greater.

Block Diagram



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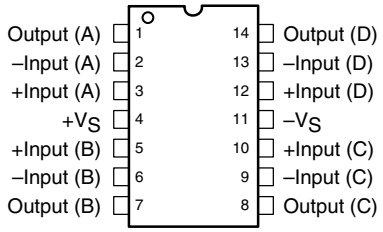
Pin Assignments



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Absolute Maximum Ratings

(beyond which the device may be damaged)[1]

Parameter		Min	Typ	Max	Units
Supply Voltage				±20	V
Input Voltage[2]				±15	V
Differential Input Voltage				30	V
Output Short Circuit Duration[3]		Indefinite			
$P_D T_A$ < 50°C	SOIC			300	mW
	PDIP			468	mW
Operating Temperature	RC4156/RC4157	0		70	°C
Storage Temperature		-65		150	°C
Junction Temperature	SOIC, PDIP			125	°C
Lead Soldering Temperature (60 seconds)	DIP			300	°C
	SOIC			260	°C
For T_A > 50°C Derate at	SOIC		5.0		mW/°C
	PDIP		6.25		mW/°C

Notes:

1. Functional operation under any of these conditions is NOT implied. Performance and reliability are guaranteed only if Operating Conditions are not exceeded.
2. For supply voltages less than ±15V, the absolute maximum input voltage is equal to the supply voltage.
3. Short circuit to ground on one amplifier only.

Operating Conditions

Parameter			Min	Typ	Max	Units
θ_{JC}	Thermal resistance			60		°C/W
θ_{JA}	Thermal resistance	SOIC		200		°C/W
		PDIP		160		°C/W

Electrical Characteristics

(V_S = ±15V, RC = 0°C ≤ T_A ≤ +70°C)

Parameters	Test Conditions	RC4156/4157			Units
		Min	Typ	Max	
Input Offset Voltage	R_S ≤ 10 kΩ			6.5	mV
Input Offset Current				100	nA
Input Bias Current				400	nA
Large Signal Voltage Gain	R_L ≥ 2 kΩ,V_{OUT} ±10V	15			V/mV
Output Voltage Swing	R_L ≥ 2 kΩ	±10			V
Supply Current			10		mA
Average Input Offset Voltage Drift			5.0		µV/°C

Electrical Characteristics

(V_S = ±15V and T_A = +25°C unless otherwise noted)

Parameters	Test Conditions	RC4156/4157			Units
		Min	Typ	Max	
Input Offset Voltage	$R_S \leq 10\ k\Omega$		1.0	5.0	mV
Input Offset Current			30	50	nA
Input Bias Current			60	300	nA
Input Resistance			0.5		MΩ
Large Signal Voltage Gain	$R_L \geq 2\ k\Omega$, V_{OUT} ±10V	25	100		V/mV
Output Voltage Swing	$R_L \geq 10\ k\Omega$	±12	±14		V
	$R_L \geq 2\ k\Omega$	±10	±13		V
Input Voltage Range		±12	±14		V
Output Resistance			230		Ω
Short Circuit Current			25		mA
Common Mode Rejection Ratio	$R_S \leq 10\ k\Omega$	80			dB
Power Supply Rejection Ratio	$R_S \leq 10\ k\Omega$	80			dB
Supply Current (All Amplifiers)	$R_L = \infty$		5.0	7.0	mA
Transient Response (4156)					
Rise Time			60		nS
Overshoot			25		%
Slew Rate		1.3	1.6		V/µS
Unity Gain Bandwidth (4156)		2.8	3.5		MHz
Phase Margin (4156)	$R_L = 2\ k\Omega$, $C_L = 50\ pF$		50		%
Transient Response (4157)	$A_V = -5$				
Rise Time			50		nS
Overshoot			25		%
Slew Rate		6.5	8.0		V/µS
Unity Gain Bandwidth (4157)	$A_V = -5$	15	19		MHz
Phase Margin (4157)	$A_V = -5$, $R_L = 2\ k\Omega$, $C_L = 50\ pF$		50		%
Power Bandwidth	$V_{OUT} = 20V_{p-p}$	20	25		kHz
Input Noise Voltage [1]	F = 20 Hz to 20 kHz		1.4	5.0	μV_{RMS}
Input Noise Current	F = 20 Hz to 20 kHz		15		pA_{RMS}
Channel Separation			108		dB

Note:

1. Sample tested only.

Typical Performance Characteristics

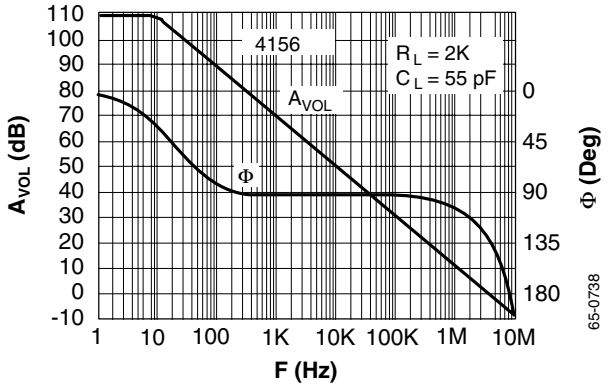


Figure 1. Open Loop Gain, Phase vs. Frequency

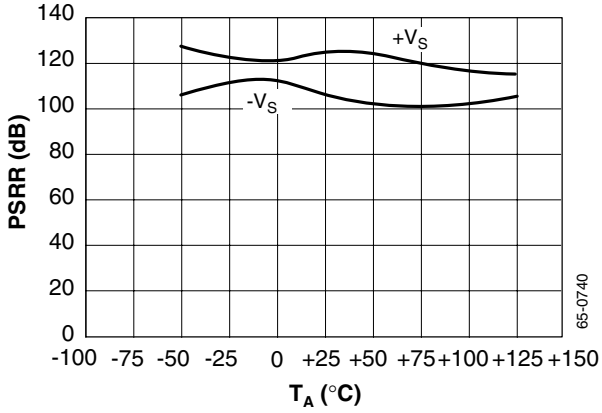
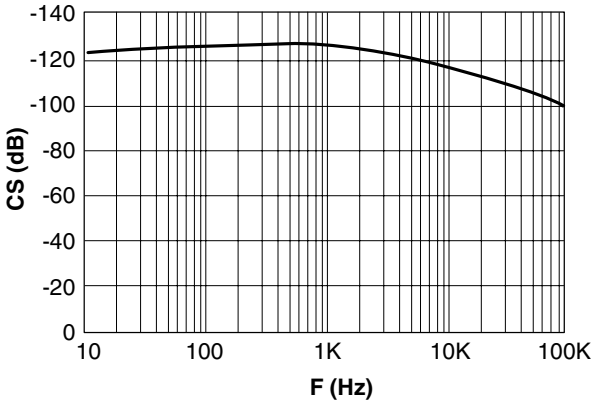


Figure 2. PSRR vs. Temperature



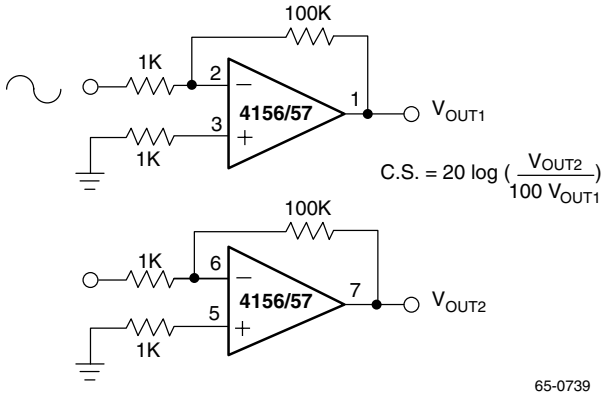


Figure 3. Channel Separation vs. Frequency

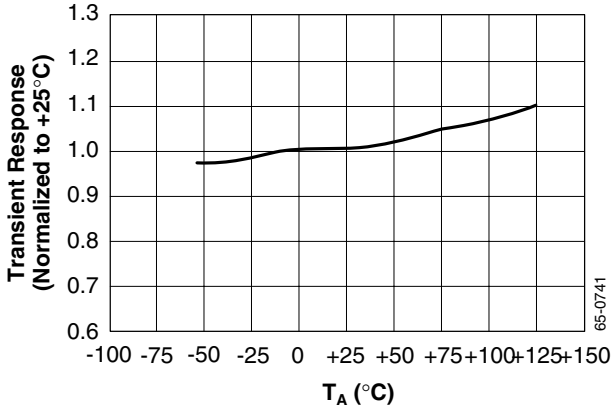


Figure 4. Transient Response vs. Temperature

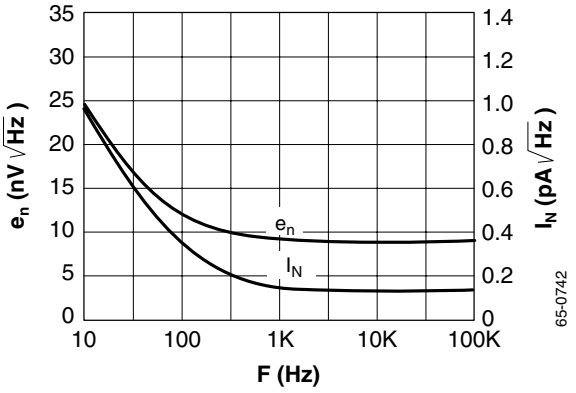


Figure 5. Input Noise Voltage, Current Density vs. Frequency

Typical Performance Characteristics (continued)

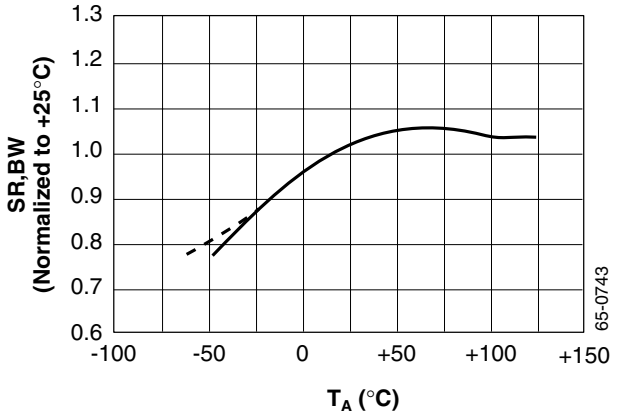


Figure 6. Slew Rate, Bandwidth vs. Temperature

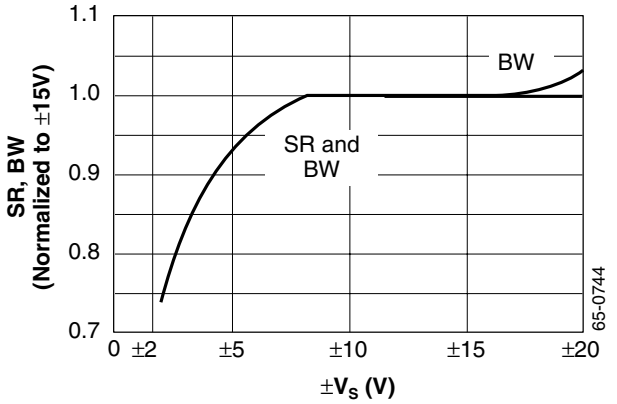


Figure 7. Slew Rate, Bandwidth vs. Supply Voltage

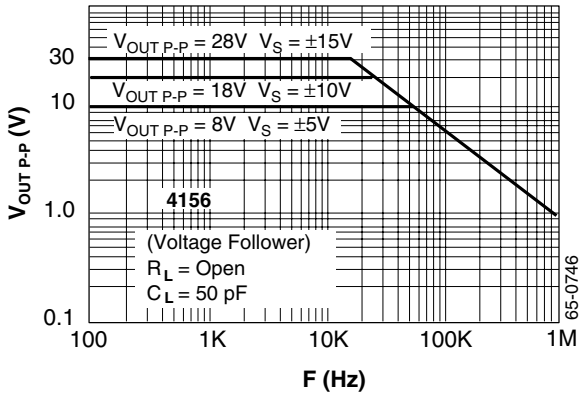


Figure 8. Output Voltage Swing vs. Frequency

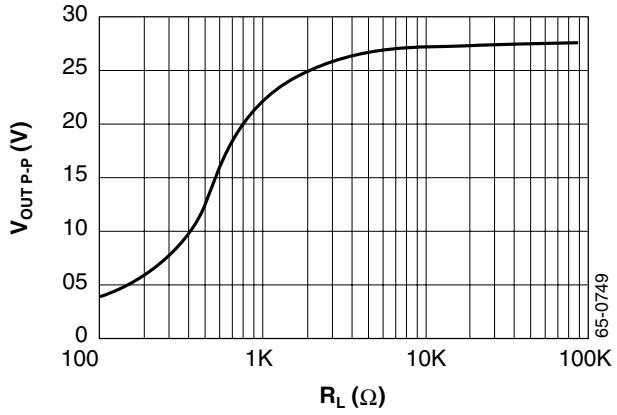


Figure 9. Output Voltage Swing vs. Load Resistance

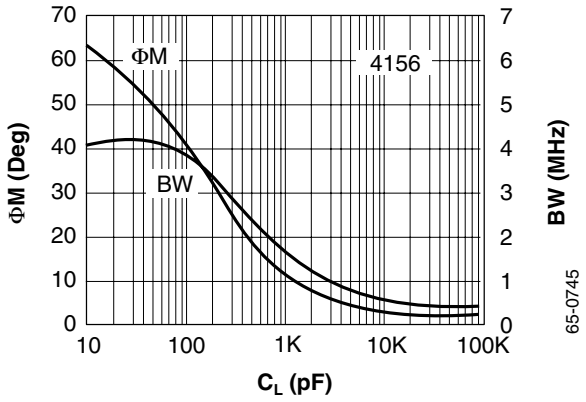


Figure 10. Small Signal Phase Margin,
Unity Gain Bandwidth vs. Load Capacitance

Typical Performance Characteristics (continued)

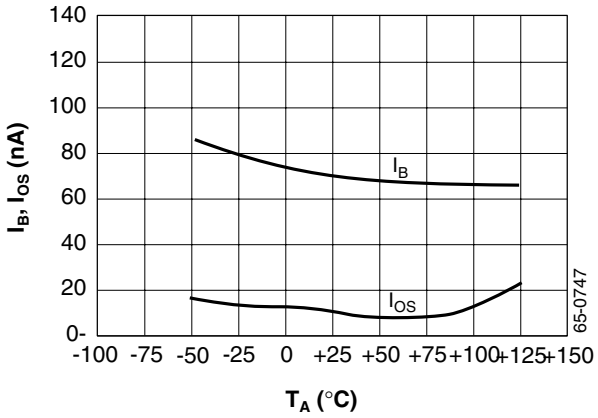


Figure 11. Input Bias, Offset Current vs. Temperature

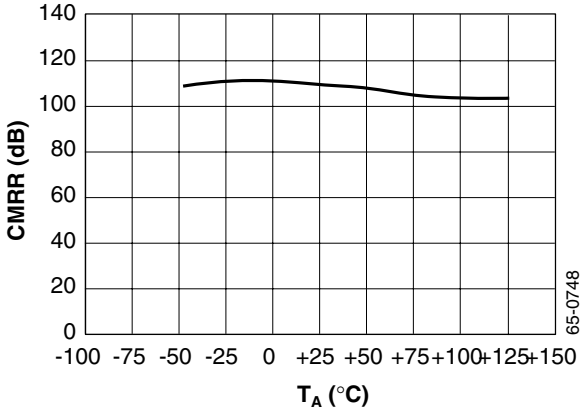


Figure 12. CMRR vs. Temperature

Applications

The RC4156 and RC4157 quad operational amplifiers can be used in almost any 741 application and will provide superior performance. The higher unity gain bandwidth and slew rate make it ideal for applications requiring good frequency response, such as active filter circuits, oscillators and audio amplifiers.

The following applications have been selected to illustrate the advantages of using the Fairchild Semiconductor RC4156 and RC4157 quad operational amplifiers.

Triangle and Square Wave Generator

The circuit of Figure 13 uses a positive feedback loop closed around a combined comparator and integrator. When power is applied the output of the comparator will switch to one of two states, to the maximum positive or maximum negative voltage. This applies a peak input signal to the integrator, and the integrator output will ramp either down or up, opposite of the input signal. When the integrator output (which is connected to the comparator input) reaches a threshold set by R1 and R2, the comparator will switch to the opposite polarity. This cycle will repeat endlessly, the integrator charging positive then negative, and the comparator switching in a square wave fashion.

The amplitude of V_2 is adjusted by varying R1. For best operation, it is recommended that R1 and V_R be set to obtain a triangle wave at V_2 with ±12V amplitude. This will then allow A3 and A4 to be used for independent adjustment of output-offset and amplitude over a wide range.

The triangle wave frequency is set by C0, R0, and the maximum output voltages of the comparator. A more symmetrical waveform can be generated by adding a back-to-back Zener diode pair as shown in Figure 14.

An asymmetric triangle wave is needed in some applications. Adding diodes as shown by the dashed lines is a way to vary the positive and negative slopes independently.

The frequency range can be very wide and the circuit will function well up to about 10 kHz. The square wave transition time at V_1 is less than 21 µS when using the RC4156.

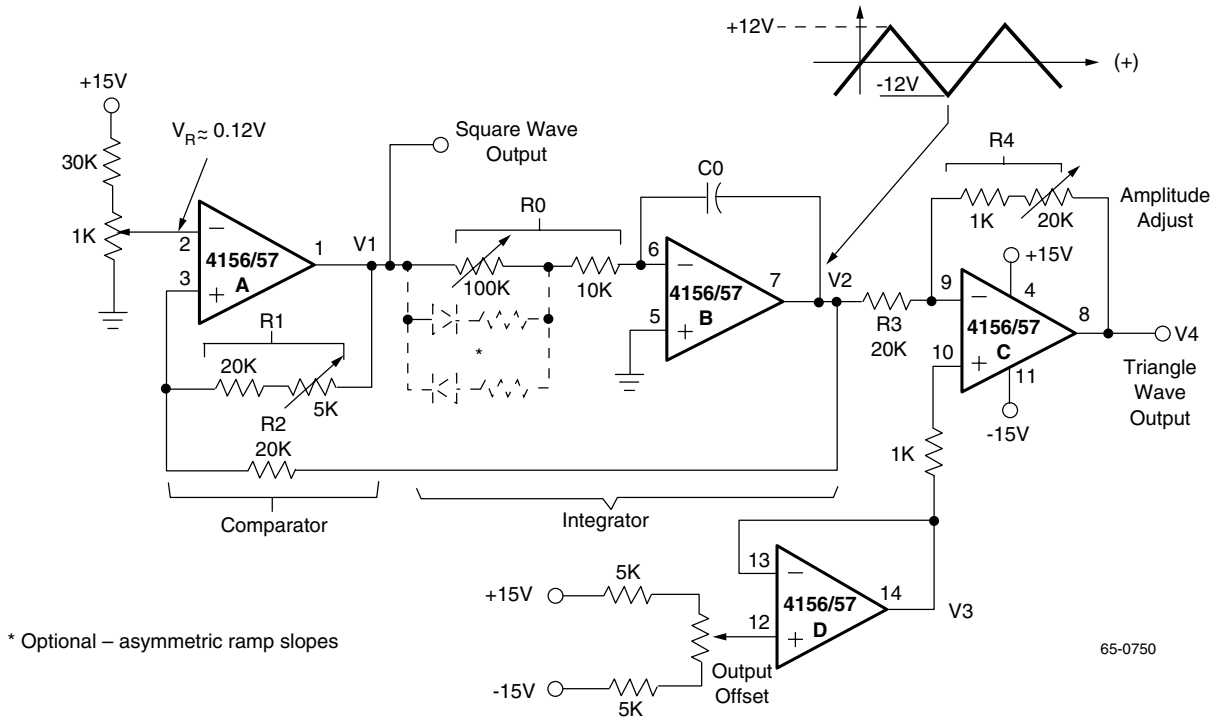


Figure 13. Triangle and Square Wave Generator

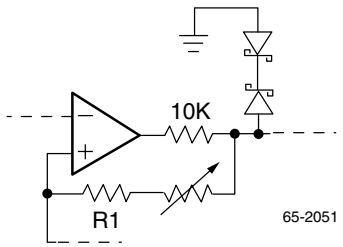


Figure 14. Triangle Generator—Symmetrical Output Option

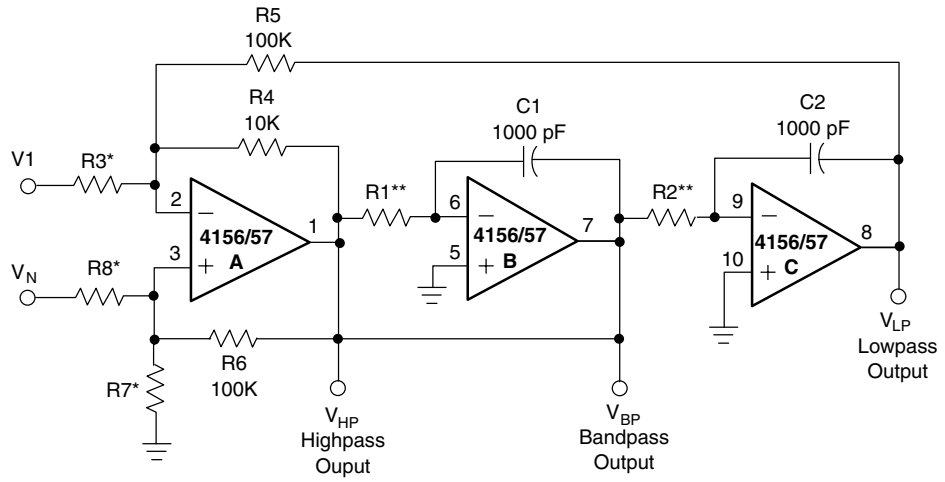
Active Filters

The introduction of low-cost quad op amps has had a strong impact on active filter design. The complex multiple-feedback, single op amp filter circuits have been rendered obsolete for most applications. State-variable active-filter circuits using three to four op amps per section offer many advantages over the single op amp circuits. They are relatively insensitive to the passive-component tolerances and variations. The Q, gain, and natural frequency can be independently adjusted. Hybrid construction is very practical because resistor and capacitor values are relatively low and the filter parameters are determined by resistance ratios rather than by single resistors. A generalized circuit diagram of the 2-pole state-variable active filter is shown in Figure 15. The particular input connections and component-values can be calculated for specific applications. An important feature of the state-variable filter is that it can be inverting or non-inverting and can simultaneously provide three outputs: lowpass, bandpass, and highpass. A notch filter can be realized by adding one summing op amp.

The RC4156 was designed and characterized for use in active filter circuits. Frequency response is fully specified with minimum values for unity-gain bandwidth, slew-rate, and full-power response. Maximum noise is specified.

Output swing is excellent with no distortion or clipping. The RC4156 provides full, undistorted response up to 20 kHz and is ideal for use in high-performance audio and telecommunication equipment.

In the state-variable filter circuit, one amplifier performs a summing function and the other two act as integrators. The choice of passive component values is arbitrary, but must be consistent with the amplifier operating range and input signal



* Input connections are chosen for inverting or non-inverting response. Values of R3,R7,R8 determine gain and Q.
** Values of R1 and R2 determine natural frequency. 65-0751

Figure 15. 2-Pole State-Variable Active Filter

characteristics. The values shown for C1, C2, R4, R5 and R6 are arbitrary. Pre-selecting their values will simplify the filter tuning procedures, but other values can be used if necessary.

The generalized transfer function for the state-variable active filter is:

$$T(s) = \frac{a_2 s^2 + a_1 s + a_0}{s^2 + b_1 s + b_0}$$

Filter response is conventionally described in terms of a natural frequency ω_0 in radians/sec, and Q, the quality of the complex pole pair. The filter parameters ω_0 and Q relate to the coefficients in T(s) as:

$$\omega_0 = \sqrt{b_0} \text{ and } Q = \frac{\omega_0}{b_0}$$

The input configuration determines the polarity (inverting or non-inverting), and the output selection determines the type of filter response (lowpass, bandpass, or highpass).

Notch and all-pass configurations can be implemented by adding another summing amplifier.

Bandpass filters are of particular importance in audio and telecommunication equipment. A design approach to bandpass filters will be shown as an example of the state-variable configuration.

Design Example Bandpass Filter

For the bandpass active filter (Figure 16) the input signal is applied through R3 to the inverting input of the summing amplifier and the output is taken from the first integrator (V_{BP}). The summing amplifier will maintain equal voltage at the inverting and non-inverting inputs (see Equation 1).

$$\frac{\frac{R3R5}{R3+R5}}{R4+\frac{R3R5}{R3+R5}} V_{HP}(s) + \frac{\frac{R3R4}{R3+R4}}{R5+\frac{R3R4}{R3+R4}} V_{LP}(s) + \frac{\frac{R4R5}{R4+R5}}{R3+\frac{R4R5}{R4+R5}} V_{IN}(s) + \frac{R7}{R6+R7} V_{BP}(s)$$

Equation 1.

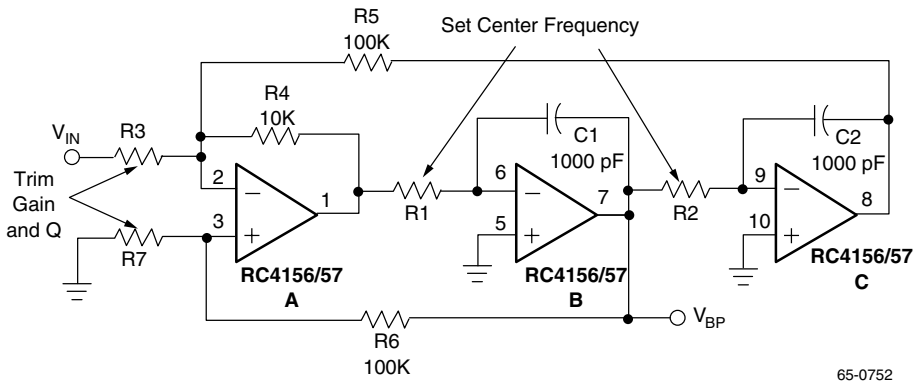


Figure 16. Bandpass Active Filter

These equations can be combined to obtain the transfer function:

$$V_{BP}(s) = -\frac{1}{R1C1S}V_{HP}(s) \quad \text{and} \quad V_{LP}(s) = -\frac{1}{R2C2S}V_{BP}(s)$$

$$\frac{V_{BP}(s)}{V_{IN}(s)} = \frac{\frac{R4}{R3}\cdot\frac{1}{R1C1}S}{S^2 + \frac{R7}{R6+R7}\left(1+\frac{R4}{R5}+\frac{R4}{R3}\right)\left(\frac{1}{R1C1}\right)S + \left(\frac{R4}{R5}\right)\left(\frac{1}{R1C1R2C2}\right)}$$

Defining 1/R1C1 as ω1, 1/R2C2 as ω2, and substituting in the assigned values for R4, R5, and R6, then the transfer function simplifies to:

$$\frac{V_{BP}(s)}{V_{IN}(s)} = \frac{\frac{10^4}{R3}\cdot\omega_1 s}{S^2 + \left[\frac{1.1+\frac{10^4}{R3}}{1+\frac{10^5}{R7}}\right]\omega_1 s + \frac{1}{\omega_1\omega_2}}$$

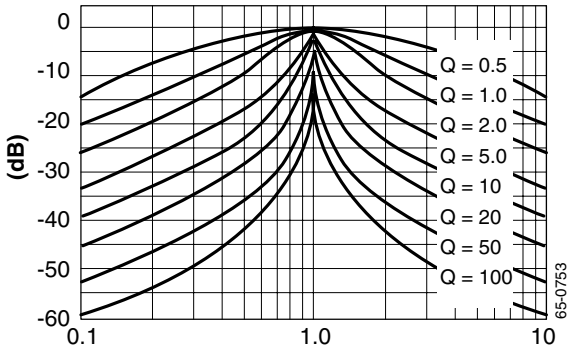
This is now in a convenient form to look at the center-frequency ω0 and filter Q.

$$\omega_0 = \sqrt{0.1\omega_1\omega_2}$$

$$\omega_0 = 10^{-9}\sqrt{0.1R1R2} \quad \text{and}$$

$$Q = \left[\frac{1+\frac{10^5}{R7}}{1.1+\frac{10^4}{R3}}\right]\omega_0$$

The frequency responses for various values of Q are shown in Figure 17.



$$\frac{\omega}{\omega_o}$$

$$\frac{V_{BP}}{V_{IN}} = \frac{\frac{\omega}{\omega_o}\,\frac{1}{Q}}{\sqrt{\left[1-\left(\frac{\omega}{\omega_o}\right)^2\right]^2 + \left(\frac{1}{Q}\,\frac{\omega}{\omega_o}\right)^2}}$$

Figure 17. Bandpass Transfer Characteristics Normalized for Unity Gain and Frequency

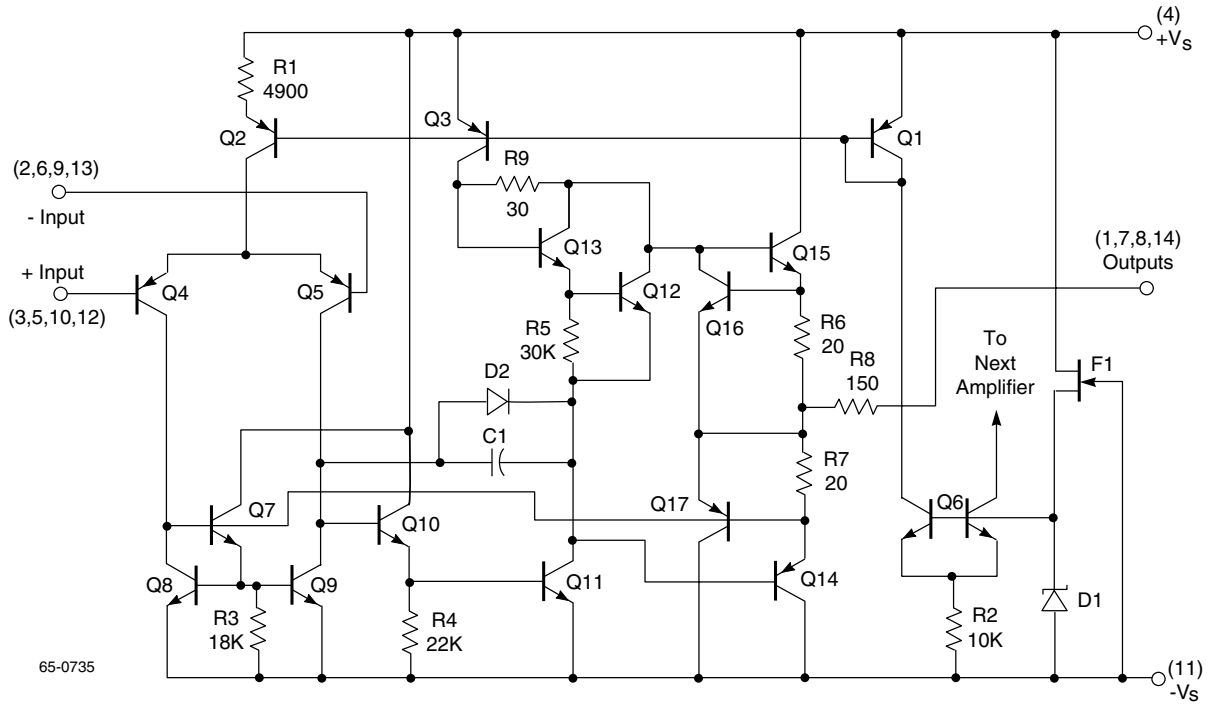
These equations suggest a tuning sequence where ω is first trimmed via R1 or R2, then Q is trimmed by varying R7 and/or R3. An important advantage of the state-variable bandpass filter is that Q can be varied without affecting center frequency ω_0.

This analysis has assumed ideal op amps operating within their linear range, which is a valid design approach for a reasonable range of ω_0 and Q. At extremes of ω_0 and at high values of Q, the op amp parameters become significant. A rigorous analysis is very complex, but some factors are particularly important in designing active filters.

1. The passive component values should be chosen such that all op amps are operating within their linear region for the anticipated range of input signals. Slew rate, output current rating, and common-mode input range must be considered. For the integrators, the current through the feedback capacitor (I = C dV/dt) should be included in the output current computations.
2. From the equation for Q, it should seem that infinite Q could be obtained by making R7 zero. But as R7 is made small, the Q becomes limited by the op amp gain at the frequency of interest. The effective closed-loop gain is being increased directly as R7 is made smaller, and the ratio of open-loop gain to closed-loop gain is becoming less. The gain and phase error of the filter at high Q is very dependent on the op amp open-loop gain at w_0.
3. The attenuation at extremes of frequency is limited by the op amp gain and unity-gain bandwidth. For integrators, the finite open-loop op amp gain limits the accuracy at the low-end. The open-loop roll-off of gain limits the filter attenuation at high frequency.

The RC4156 quad operational amplifier has much better frequency response than a conventional 741 circuit and is ideal for active filter use. Natural frequencies of up to 10 kHz are readily achieved and up to 20 kHz is practical for some configurations. Q can range up to 50 with very good accuracy and up to 500 with reasonable response. The extra gain of the RC4156 at high frequencies gives the quad op amp an extra margin of performance in active-filter circuits.

Schematic Diagram (1/4 shown)



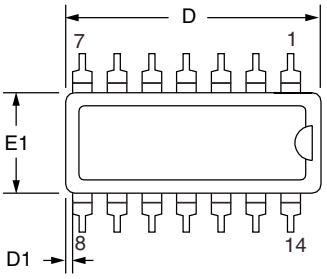
Mechanical Dimensions (continued)

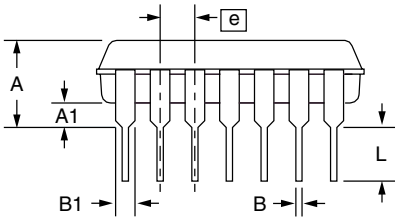
14-Lead Plastic DIP Package

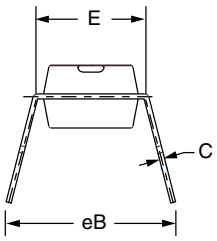
Symbol	Inches		Millimeters		Notes
	Min.	Max.	Min.	Max.	
A	—	.210	—	5.33	
A1	.015	—	.38	—	
A2	.115	.195	2.93	4.95	
B	.014	.022	.36	.56	
B1	.045	.070	1.14	1.78	
C	.008	.015	.20	.38	4
D	.725	.795	18.42	20.19	2
D1	.005	—	.13	—	
E	.300	.325	7.62	8.26	
E1	.240	.280	6.10	7.11	2
e	.100 BSC		2.54 BSC		
eB	—	.430	—	10.92	
L	.115	.200	2.92	5.08	
N	14		14		5

Notes:

1. Dimensioning and tolerancing per ANSI Y14.5M-1982.
2. "D" and "E1" do not include mold flashing. Mold flash or protrusions shall not exceed .010 inch (0.25mm).
3. Terminal numbers are shown for reference only.
4. "C" dimension does not include solder finish thickness.
5. Symbol "N" is the maximum number of terminals.







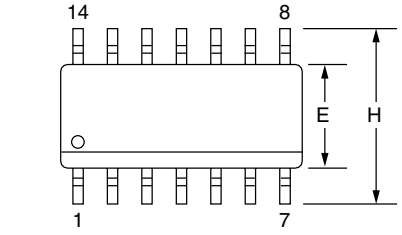
Mechanical Dimensions (continued)

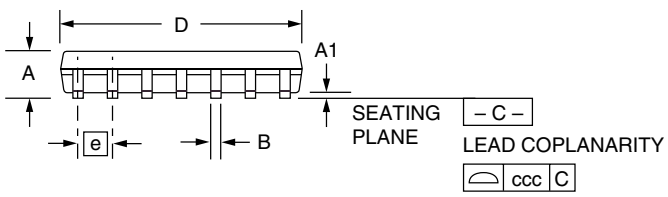
14-Lead SOIC Package

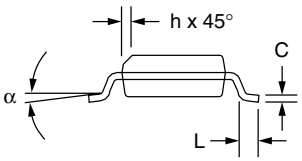
Symbol	Inches		Millimeters		Notes
	Min.	Max.	Min.	Max.	
A	.053	.069	1.35	1.75	
A1	.004	.010	0.10	0.25	
B	.013	.020	0.33	0.51	
C	.008	.010	0.19	0.25	5
D	.336	.345	8.54	8.76	2
E	.150	.158	3.81	4.01	2
e	.050 BSC		1.27 BSC		
H	.228	.244	5.79	6.20	
h	.010	.020	0.25	0.50	
L	.016	.050	0.40	1.27	3
N	14		14		6
α	0°	8°	0°	8°	
ccc	—	.004	—	0.10	

Notes:

1. Dimensioning and tolerancing per ANSI Y14.5M-1982.
2. "D" and "E" do not include mold flash. Mold flash or protrusions shall not exceed .010 inch (0.25mm).
3. "L" is the length of terminal for soldering to a substrate.
4. Terminal numbers are shown for reference only.
5. "C" dimension does not include solder finish thickness.
6. Symbol "N" is the maximum number of terminals.







Ordering Information

Product Number	Temperature Range	Screening	Package	Package Marking
RC4156N	0° to 70°C	Commercial	14 Pin Plastic DIP	RC4156N
RC4157N	0° to 70°C	Commercial	14 Pin Plastic DIP	RC4157N
RC4156M	0° to 70°C	Commercial	14 Pin Wide SOIC	RC4156M
RC4157M	0° to 70°C	Commercial	14 Pin Wide SOIC	RC4157M

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2. A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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